


# Review of models for large scale manufacturing Networks

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SMMSO 2017

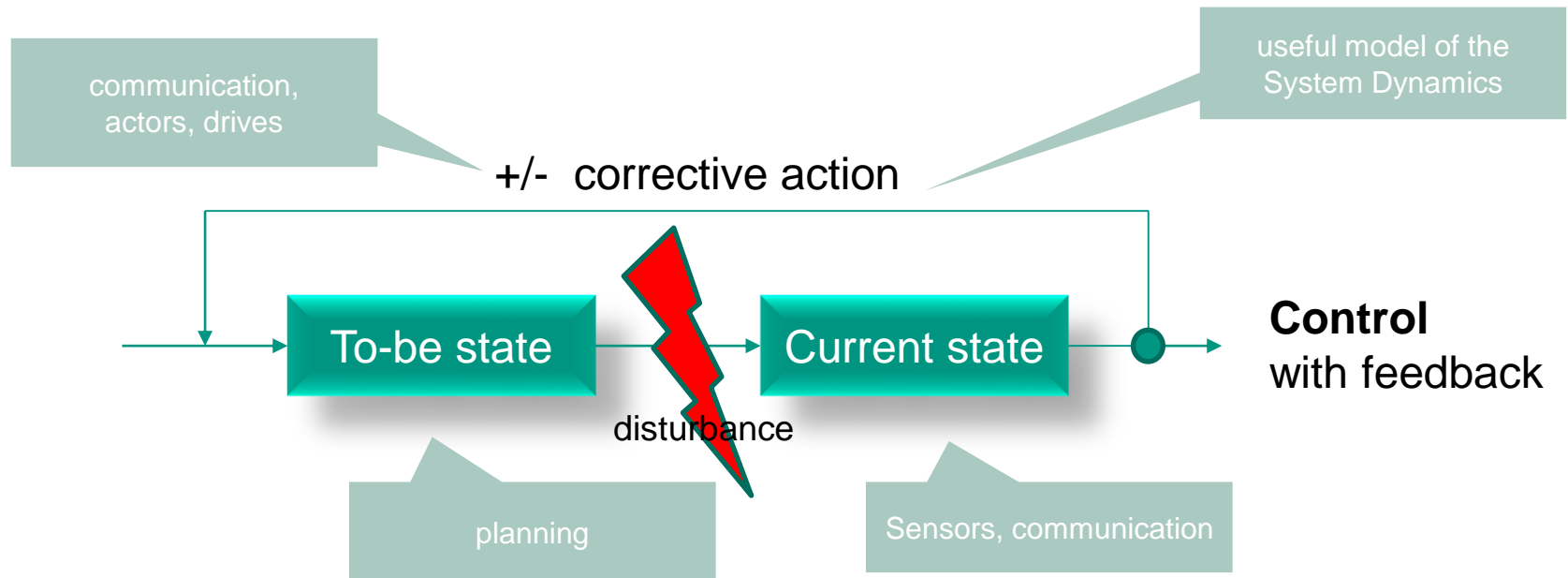
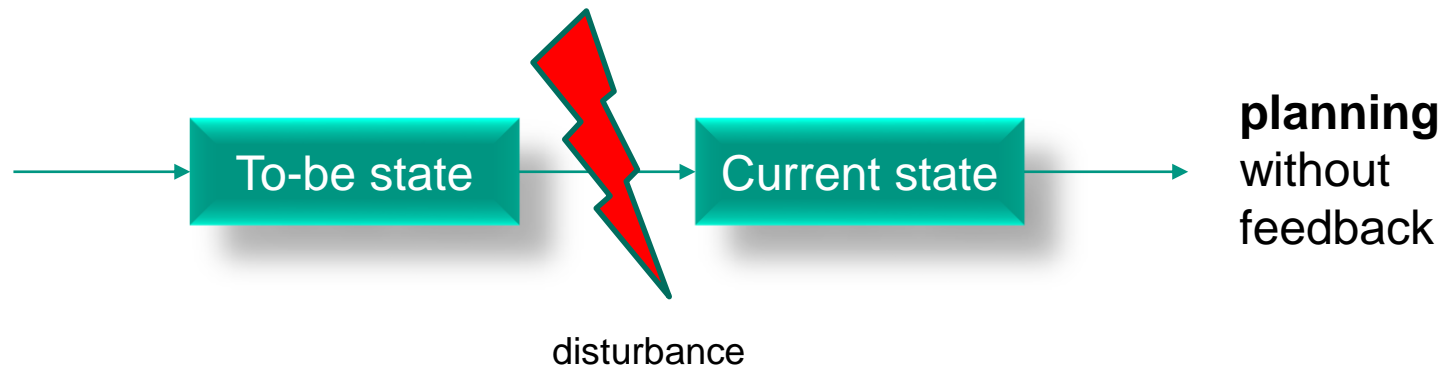
Institute for Material Handling and Logistics (IFL), KIT, University of Thessaly 



# Outline Presentation

- ❑ **The Research Idea –**
  - ❑ **Controlling Supply Networks as Cyber-physical Systems**
  - ❑ **Cyber-Physical Systems – Definition and an Example**
- ❑ **The Research Project *Productive4.0***
  - ❑ Positioning of the Project
  - ❑ Scope of the project
  - ❑ Project Structure
- ❑ **The Methods and Tools of WP4 & WP5 of *Productive4.0***
- ❑ **Literature Review**
- ❑ **Conclusion**

# Real-time Control of any Physical System



# Differences between Factories and Airplanes

- Control model available
- Continuous state, continuous corrective actions
- High frequency of small corrections
- Most planes inherently stable, stability a key factor
- One model

- Control model missing
- discrete state, discrete corrective actions
- No defined frequency of corrective actions, control frequency rather low
- Stability issues not known
- Multi-level model (if at all)

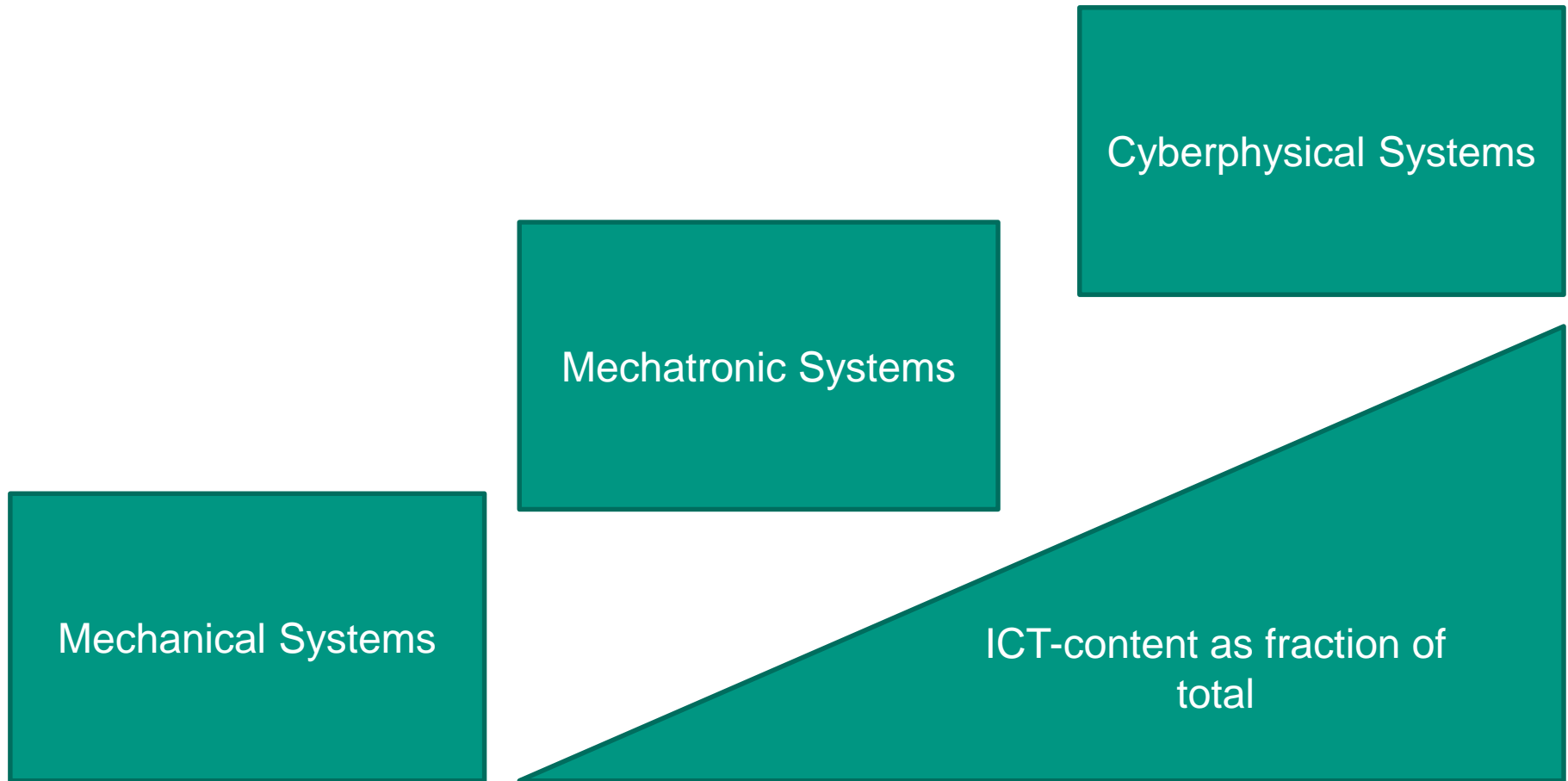


Airbus A320neo (airbus.com)



Aerial view of the Bosch semiconductor plants Reutlingen (kka-online.de)

# What are Cyberphysical Systems



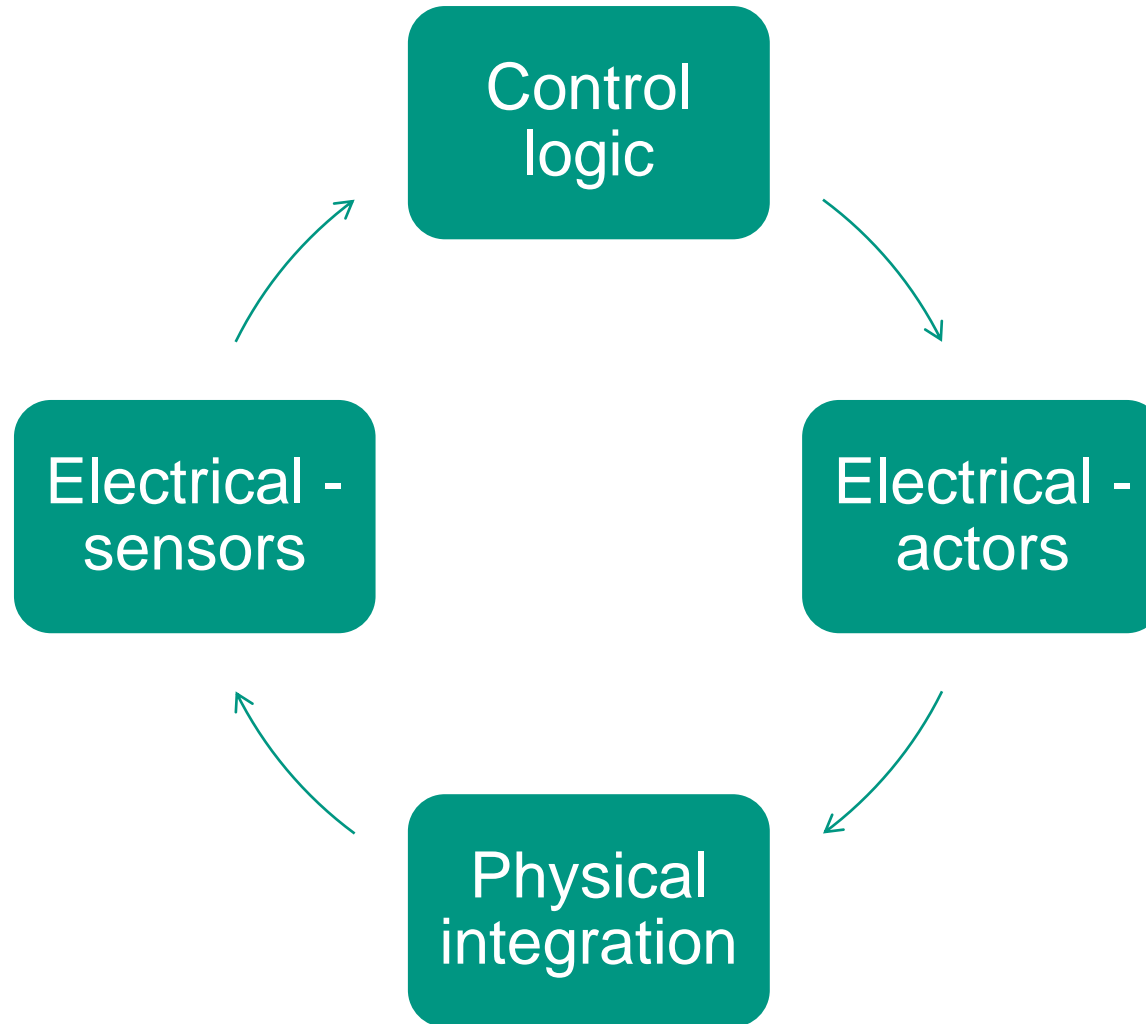
# Cyberphysical Systems: Background

- Initiative of National Science Foundation (USA) 2006
- **Cyber**: computer based, digital control and communication
- **Physisch**: artificial or natural systems, underlying the laws of physics and working in continuous real time
- **Cyberphysical System**: autonomous control of physical systems based on digital, autonomous „comprehension“ of the system and it's environment

# Why do we need CPS?

- A simple example from Material Handling

# Reconfiguration of today's material handling systems needs changes in several levels

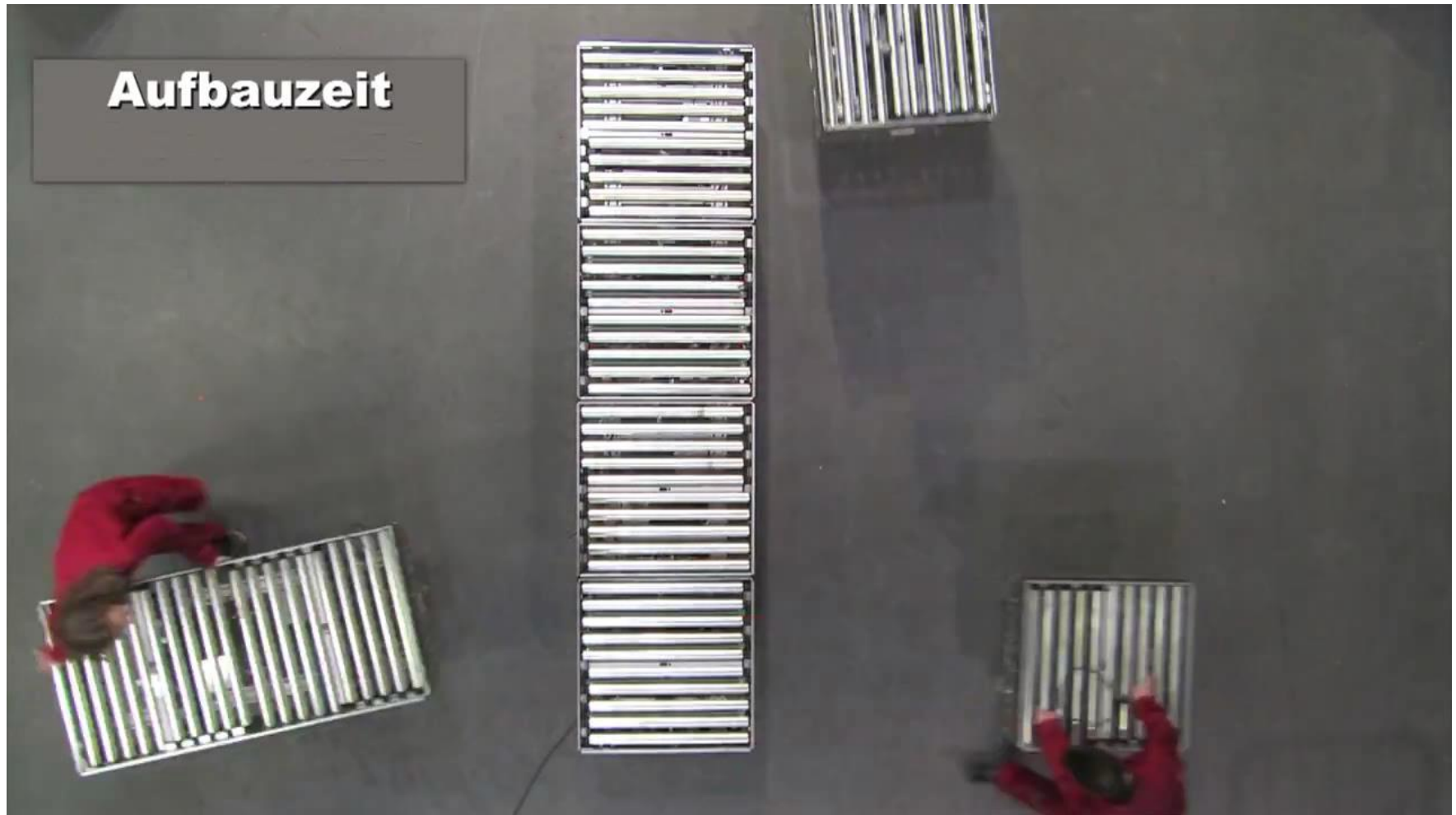




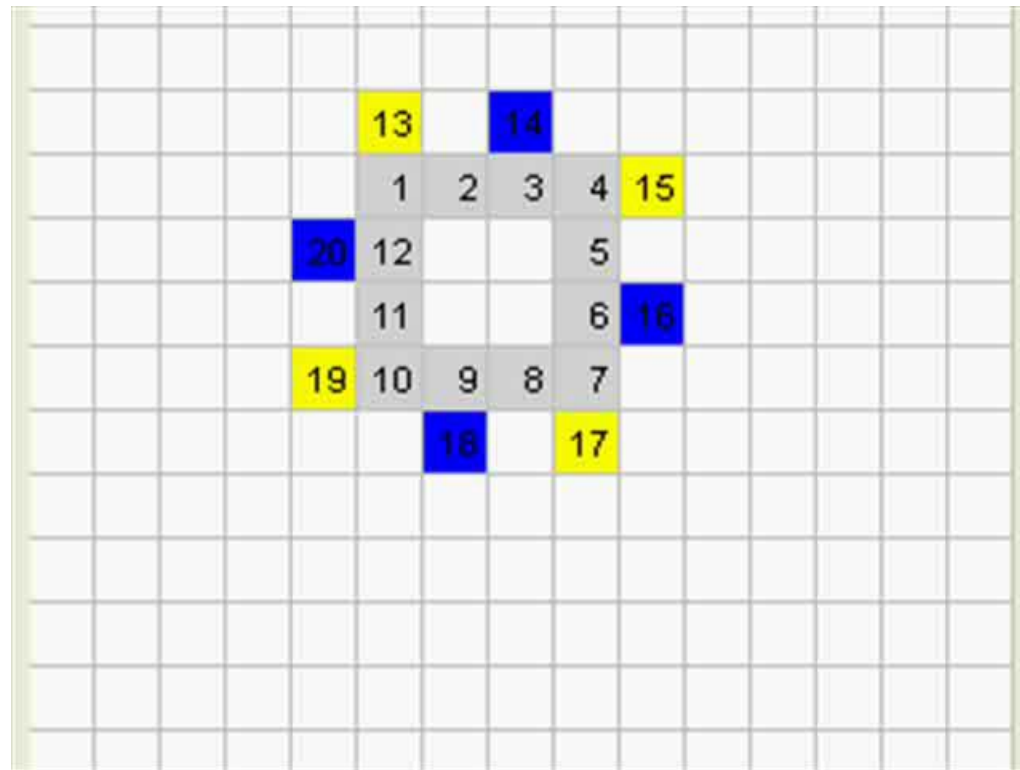
# FlexConveyor



# Flexconveyor – Assembly and Modification



# Emerging Behaviour



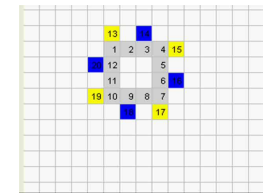
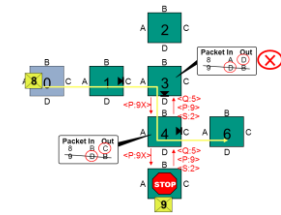
# GridStore



# Characteristics Flexconveyor as a CPS

## ■ Cyber:

- Local Control can get enough information which is necessary to „understand“ the state of the system and its environment
- Clear control system – „to be state“ clearly defined, „is-state“ clearly defined
- There is always an action to get the system closer to it's to be state
- Can make all necessary decisions



## ■ Physical:

- System is able to move real stuff
- Is able to execute all the decisions
- Provides cyber-part with sufficient feed back of real situation

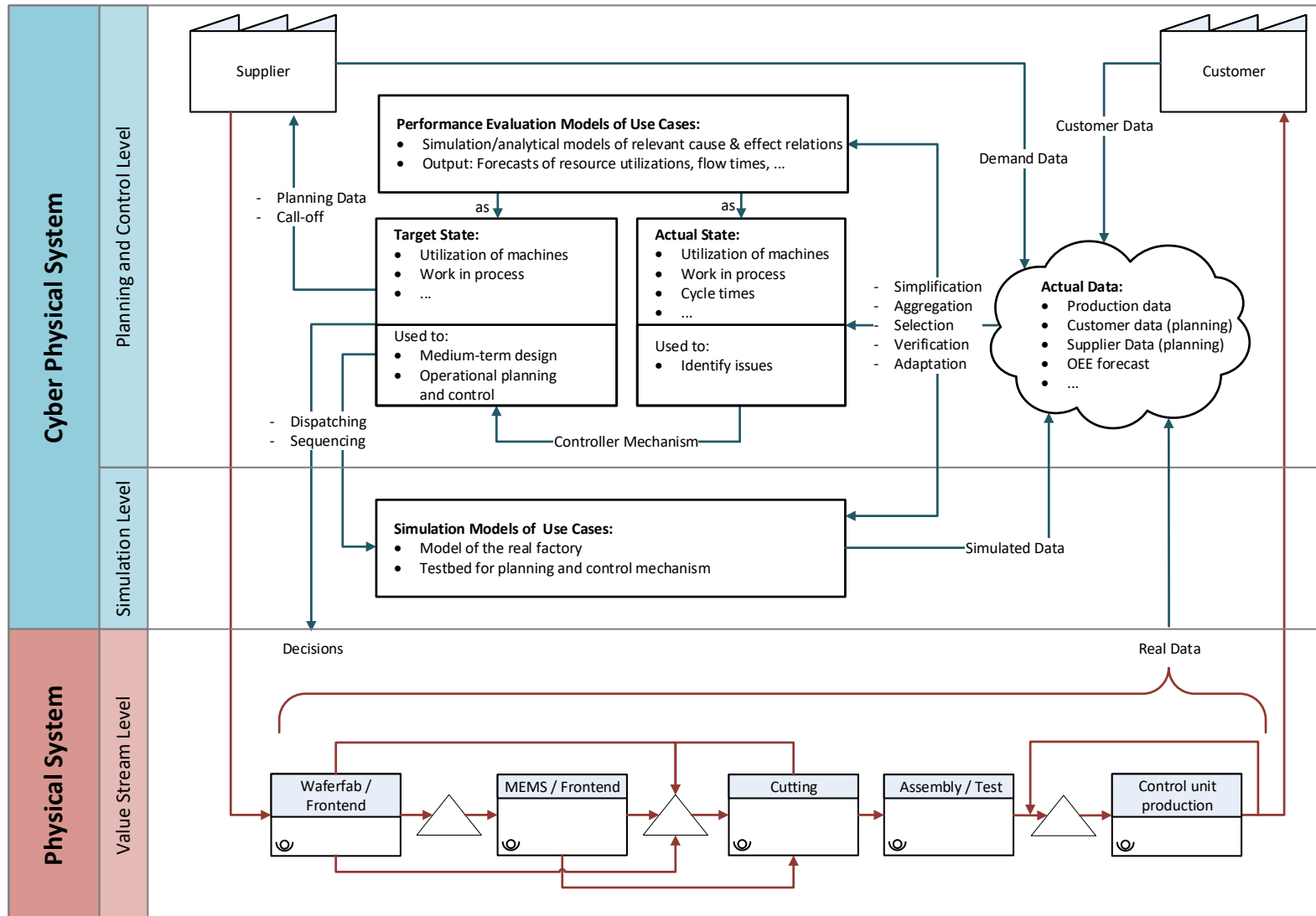


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- The Methods and Tools of WP4 & WP5 of *Productive4.0*
- Literature Review
- Conclusion



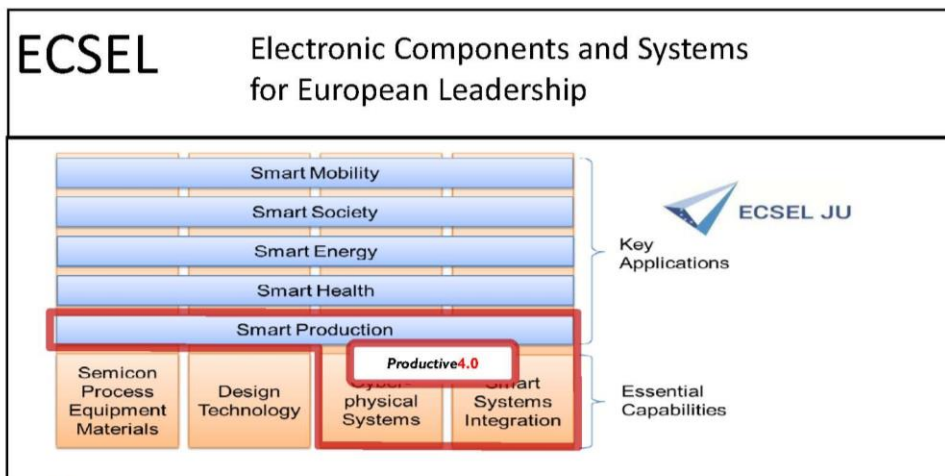
# The Research Idea: Semiconductor Production Systems as Cyber Physical Systems



# The Research Project *Productive4.0*

## □ Positioning of the Project

EC Horizon2020



ECSEL Innovation Action & Lighthouse

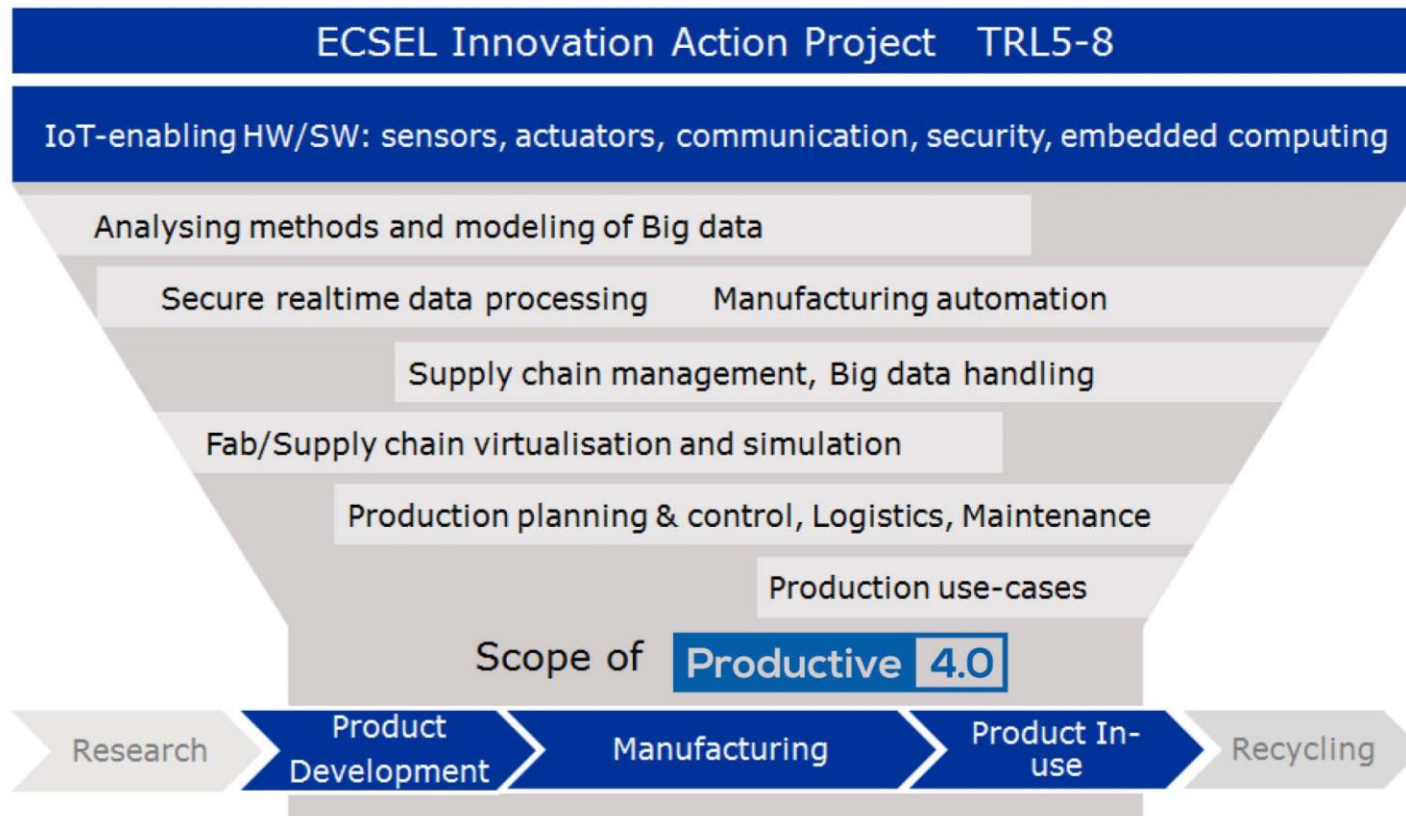
**Productive 4.0**

Electronics and ICT as enabler for digital industry and optimized supply chain management covering the entire product lifecycle



# The Research Project *Productive4.0*

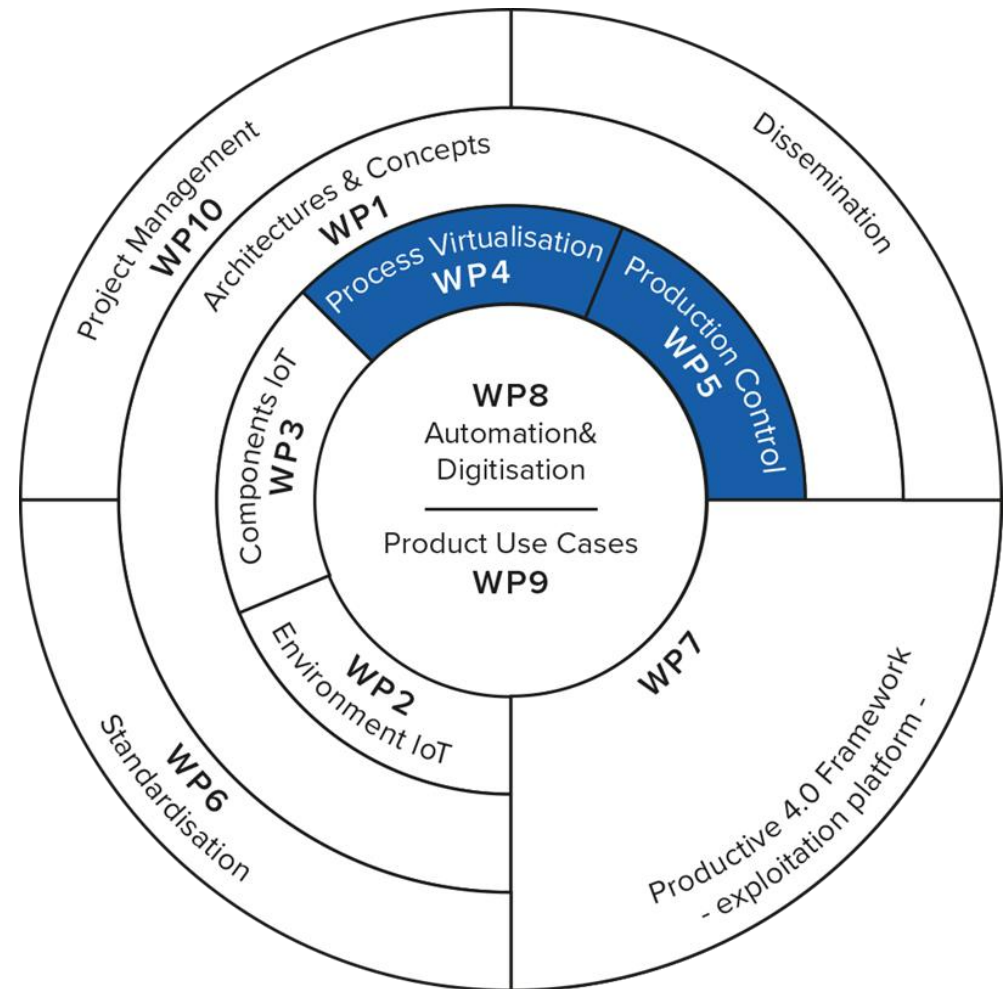
## □ Scope of the project



# The Research Project *Productive4.0*

## □ Project Structure

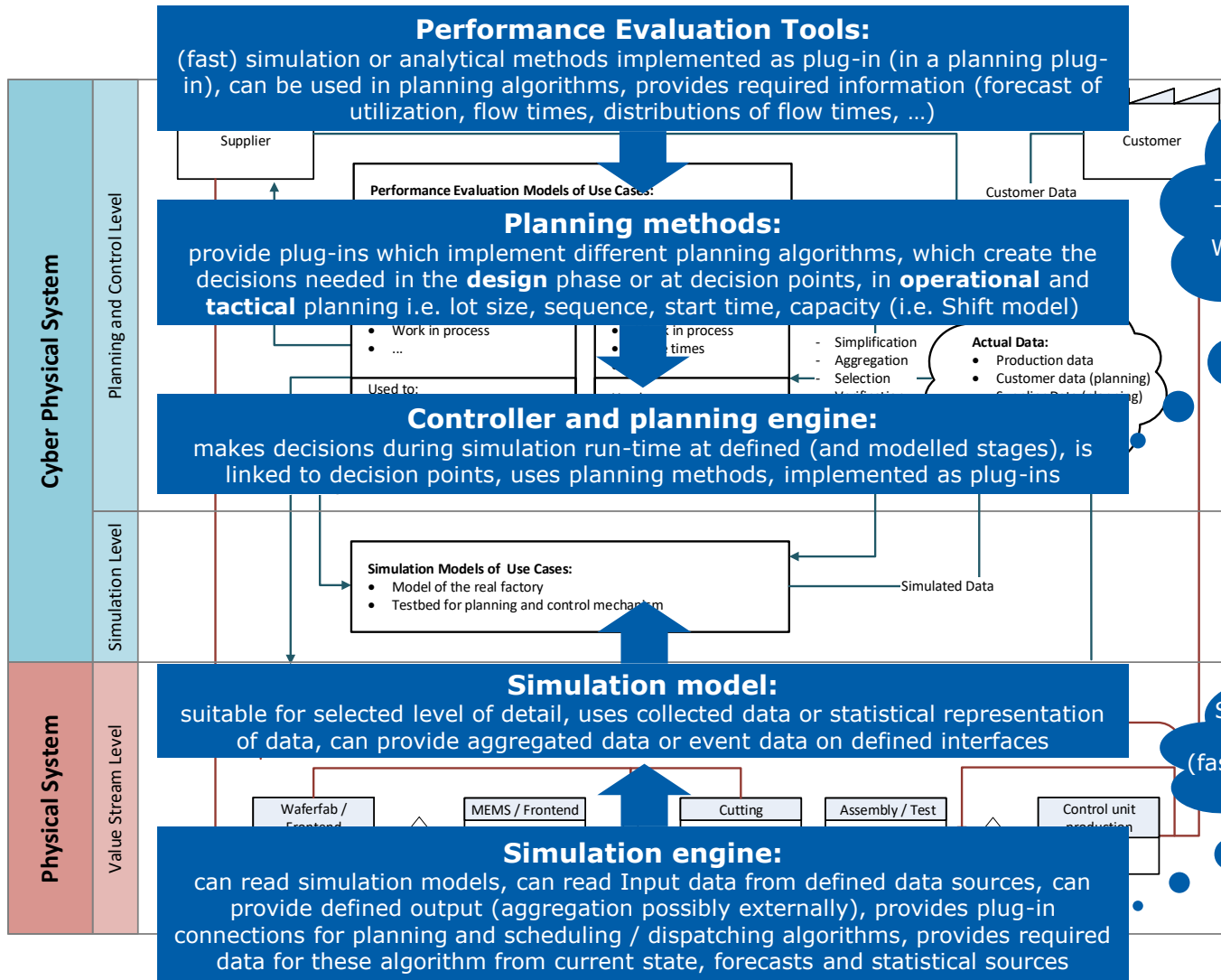
- Work Package 4  
Develop a virtual simulation framework for modelling complex manufacturing systems and supply chains
  
- Work Package 5  
Develop Methods for Design Planning and Control of manufacturing systems and the supply network



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# The Methods and Tools of WP4 & WP5 of *Productive4.0*



Data access for planning and controller methods

- Through simulation engine (likely)
- Directly

What about historic data, statistics, future data (forecasts)

Same or different simulation engines for performance evaluation (fast simulation) used in decision making and in testbench or different ones?

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# Literature Review - Characteristics of modelling a large scale manufacturing networks

Reference	Target	Model		Considered Characteristics								Result
		Type	Time	Reentrance	Blocking	Arrival Process	Service Process	Multi-Server	Service Disciplines	Batches	Downtimes	
Morrison and Martin (2007) Kim and Morrison (2011)	D	Queuing station	AC			G	G	x	FCFS		x	Cycle Time
Ding et. al (2007)	D	Markov chain model	AC			M	M	x	GEO	x	x	Cycle Time
Akhavan-Tabaaetabi et al. (2012)	D	State-dependent Markov chain model	AC			G	G	x	FCFS		x	Work-in-Process Cycle Time
Grosbard et al. (2013)	D	Open queuing network	AC	x		G	G	x	FCFS	x	x	Cycle Time Waiting Time
Sagron et al. (2015)	D	Open queuing network	AC			G	G		FCFS TP		x	Waiting Time
Scholl and Domaschke (2000)	D	Discrete event simulation	S	x	x	G	G	x	ESD		x	Cycle Time
Sivakumar and Chong (2001)	D	Discrete event simulation	S	x	x	G	G	x	ESD		x	Cycle Time
Pearn et al. (2009)	D	Fitted Gamma distribution	AC			-	-		-			Waiting Time Cycle Time
Tai et al. (2012)	D	Fitted Weibull distribution	AC			-	-		-			Waiting Time Cycle Time
Akhavan-Tabatabaei et al. (2009)	D	Flow Analysis Model	AC			-	-		-		x	Work-in-Process Cycle Time

Target: D – Design

Time: AC - Analytical Continuous, S - Simulation

# Literature Review - Characteristics of modelling a large scale manufacturing networks

Reference	Target	Model		Considered Characteristics								Result
		Type	Time	Reentrance	Blocking	Arrival Process	Service Process	Multi-Server	Service Disciplines	Batches	Downtimes	
Veeger et al. (2010a, 2010b)	D	EPT-based aggregate simulation model	AC			G	G	x	FCFS		x	Cycle Time
Veeger et al. (2011)	D	EPT-based aggregate simulation model	S			G	G		FCFS LCFS		x	Cycle Time
Can and Heavey (2017)	D	EPT-based discrete event simulation	S		x	M	M	x	FCFS		x	Cycle Time
Yang et al. (2011)	D	Simulation-based metamodeling	S			-	-	x	TP			Cycle Time
Yang (2010)	D	Neural network metamodeling	S			-	-	x	TP			Cycle Time
Hsieh et al. (2014)	D	Progressive simulation metamodeling	S			-	-		TP	x		Cycle Time
Schelasin (2011, 2013)	D	Static capacity model Queueing station	AC			G	G	x	FCFS		x	Waiting Time Cycle Time
Zisgen and Meents (2008) Brown et al. (2010)	D	Open queuing network	AC	x		G	G	x	FCFS	x	x	Cycle Time Queue Lengths
Zarifoglu et al (2013)	O	Queueing Model	AC			G	G		FCFS	x		Optimal Lot Size
Chang (2017)	O	Simulation	AC	x		G	G	x	TP	x		Optimal Product Mix

Target: D – Design, O - Optimisation Time: AC - Analytical Continuous, S - Simulation

# Literature Review - Characteristics of modelling a large scale manufacturing networks

Reference	Target	Model		Considered Characteristics								Result
		Type	Time	Reentrance	Blocking	Arrival Process	Service Process	Multi-Server	Service Disciplines	Batches	Downtimes	
Wang and Wang (2007)	O	Simulation	S	x		G	D	x	FCFS	x		Optimal Lot Size
Akhavan-Tabatabaei et al. (2011)	O	Simulation	S	x		M	M		FCFS		x	Optimal Lot Release
Fowler et al. (2002)	O	Queueing Station	AC			G	G	x	FCFS	x		Optimal Batch Size
Kuo et al. (2011)	O	Neural Network	AC			G	G	x	FCFS	x	x	Reduce Cycle Time
Li et al. (2010)	O	Queueing Network	AC		x	M	M		FCFS		x	Optimal WIP level
Wang et al. (2013)	O	Neural Network	AC			G	G		OPT			Optimize Service Discipline
Chien et al. (2012)	O	Neural Network	AC			-	-		-			Reduce Cycle Time
Yao et al. (2004)	O	Modelling Framework	AC			-	-		-		x	Maintenance Scheduling
Ramirez-Hernandez et al. (2010)	O	Simulation	AC			-	-		-		x	Maintenance Scheduling
Kalir(2013)	O	Queueing Station	AC			G	G	x	FCFS		x	Optimize FM Splitting

Target: O - Optimisation

Time: AC - Analytical Continuous, S - Simulation



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## Conclusion and future research

- ❑ Usage of simulation and analytical models for the purpose of performance evaluation and especially cycle time estimation has been documented several times.
- ❑ Focus was usually set on an average cycle time, not on a percentile of the cycle time distribution.
- ❑ Dispatching and sequencing rules have also been studied, however, the impact on guaranteed performance figures is still open.
- ❑ Neural networks seem to be useful, when some data points for the system are available and the gaps between these data points have to be filled.
- ❑ Hybrid methods make use of the higher computing power available today, using combined knowledge from several sources.

**Integration of data collection, planning algorithms and performance prediction of guaranteed cycle times with a high probability is an open task.**

# WP4 & 5 Process Virtualisation + Production Control

## 1. Overview

### Partners

- INFINEON TECHNOLOGIES AG
- Robert Bosch Gesellschaft mit beschränkter Haftung
- SAP SE
- SIMPLAN AG
- FRAUNHOFER GESELLSCHAFT ZUR FOERDERUNG DER ANGEWANDTEN FORSCHUNG E.V.
- FORTISS GMBH
- KARLSRUHER INSTITUT FUER TECHNOLOGIE
- UNIVERSITAET MANNHEIM
- UNIVERSITAET ZU KOELN
- AVL LIST GMBH
- INFINEON TECHNOLOGIES AUSTRIA AG
- UNIVERSITAET KLAGENFURT
- COMMISSARIAT A L ENERGIE ATOMIQUE ET AUX ENERGIES ALTERNATIVES
- ECOLE NATIONALE SUPERIEURE DES MINES DE SAINT-ETIENNE
- STMICROELECTRONICS CROLLES 2 SAS
- APPLIED MATERIALS BELGIUM
- DANOBAT
- Savvy Data Systems S.L.
- ENGINE POWER COMPONENTS GROUP EUROPE SL
- TRIMEK SA
- ULMA EMBEDDED SOLUTIONS S COOP
- IDEKO S COOP
- ASOCIACION DE EMPRESAS TECNOLOGICAS INNOVALIA
- MONDRAGON SISTEMAS DE INFORMACION
- MONDRAGON ASSEMBLY S.COOP
- PANEPISTIMIO THESSALIAS
- CENTRO DI PROGETTAZIONE, DESIGN & TECNOLOGIE DEI MATERIALI
- LFOUNDRY SRL
- POLITECNICO DI MILANO
- Statwolf Ltd.
- UNIVERSITY OF LIMERICK
- Infineon Technologies Ireland Ltd
- Infineon Technologies Cegléd Kft.
- UNGER FABRIKKER AS
- PREDIKTOR AS
- TELLU AS
- HOGSKOLEN I OSTFOLD
- STIFTELSEN SINTEF
- KOC UNIVERSITY

→ WP4: 26 partners, 611 person months

→ WP5: 39 partners, 1.256 person months

## Next steps

- Productive 4.0 is an „innovation action“, if we do want to do more research we need:
  - Either a „Research and Innovation Action“ and/or a
  - Marie Skłodowska-Curie Action (or something similar)
- Find a way to include researchers from other continents (Americia, Asia,.....)

# Acknowledgment

This research is supported by the ECSEL-joint undertaking under grant agreement no. 737459. This joint undertaking receives support from the EU-Horizon 2020 research and innovation program and national funding

## Thank you for your attention!



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