# Approaches for machine selection and buffer allocation in stochastic flow lines 

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(1) Problem and motivation
(2) Conceptual optimization model
(3) Brute force MIP model
4. LocalSolver plus flow line decomposition
(5) Elements of a Branch \& Bound approach
(6) No numerical results, but ...

## Stochastic flow lines with alternative machines



## Problem

- Serial production process
- Single product with target production rate $P R^{\text {min }}$
- Decision I: Selection of one the alternative machines $j=1, \ldots, J_{s}$ with stochastic processing times $T_{s, j}$ for each station $s$
- Decision II: Capacity $b_{k}$ of the buffer behind station $s=1, \ldots, S-1$
- Objective: Minimize required capital budget for machines and buffers


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## Conceptual model

$$
\begin{array}{ll}
\operatorname{Min}=\sum_{s=1}^{S} \sum_{j=1}^{J_{s}} c r_{s, j}^{M} \cdot v_{s, j}+\sum_{s=1}^{S-1} c r_{s}^{B} \cdot x_{s} & \\
\sum_{j=1}^{J_{s}} v_{s, j}=1, & s=1, \ldots, S \\
P R(\underline{v}, \underline{x}) \geq P R^{\min } & \\
v_{s, j} \in\{0,1\}, & s=1, \ldots, S ; j=1, \ldots, J_{s} \\
x_{s} \in\{0,1,2,3, \ldots .\}, & s=1, \ldots, S-1
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Difficulties: $P R(\underline{v}, \underline{x})$ non-linear, no closed-form expression, integrality constraints on decision variables

## Solving the model

## Dimensions:

- Performance evaluation methodology
- Optimization methodology


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Approaches:

- Simulation optimization in an LP
- LocalSolver plus decomposition
- Branch \& Bound plus decomposition


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- $W_{0}$ work piece for warm-up phase of the line
- Very general and flexible, very time-consuming
- Limited usefulness, computation of reference values

Min $=\sum_{s=1}^{S} \sum_{j=1}^{J_{s}} c r_{s, j}^{M} \cdot V_{s, j}+\sum_{s=1}^{S-1} c r_{s}^{B} \cdot X_{s}$
$\sum_{j=1}^{J_{s}} V_{s, j}=1$,

$$
\begin{align*}
& \forall s  \tag{2}\\
& \forall s, \forall w  \tag{3}\\
& \forall s \leq S-1, \forall w  \tag{4}\\
& \forall s, \forall w \leq W-1 \\
& \forall s \leq S-1, \forall b, \forall w \leq W-b \\
& \forall s \leq S-1 \\
& \forall s \leq S-1
\end{align*}
$$

$X S_{s, w}+\sum_{j=1}^{J_{s}} d_{s, j, w} \cdot V_{s, j} \leq X F_{s, w}$,
$X F_{s, w} \leq X S_{s+\mathbf{1}, w}$,
$X F_{s, w} \leq X S_{s, w+\mathbf{1}}$,
$X F_{S, W}-X F_{S, W_{0}} \leq \frac{W-W_{0}}{P R^{\min }}$
$X S_{s+\mathbf{1}, w}-X F_{s, w+b} \leq M \cdot\left(1-Y_{s, b}\right)$,
$\sum_{b=0}^{B_{s}} Y_{s, b}=1$,
$X_{s}=\sum_{b=0}^{B_{s}} b \cdot Y_{s, b}$,

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## LocalSolver-Approach

LocalSolver

## Mathematical optimization solver

Having modeled your optimization problem using common mathematical operators, LocalSolver provides you with high-quality solutions in short running times. Based on a heuristic search approach combining different optimization techniques, Local Solver scales up to millions of variables, running on basic computers. LocalSolver includes an innovative math modeling language for fast prototyping and lightweight object-oriented APIs for full integration, which makes it easy to use and deploy on any platform

- Solve highly nonilinear problems
- Quality solutions in seconds
- Scale up to millions of variables
- Innovative math modeling language
- Easy APis for C++, Java, .NET, Python
- Simple and transparent pricing
- Dedicated and responsive support
- Free for academics
- Commercial software, academic licenses
- Heuristic search algorithms
- Combinatorial problems, discrete decision variables
- Specific math-modeling language
- APls for $\mathrm{C}++$, Python etc.
- New cool feature: Native functions !!!


## Code Example

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Use of the $\mathrm{C}++\mathrm{API}$ :
// Exactly one machine is selected per station
for (int $\mathrm{i}=0$; $\mathrm{i}<\mathrm{nbStations} ; \mathrm{i}++$ ) \{ LSExpression nbMachinesSelected = MyModel.sum(); for (int $\mathrm{j}=0$; $\mathrm{j}<\mathrm{nbCandidateMachines[i];} \mathrm{j}++$ ) $\{$ nbMachinesSelected $+=$ X[i][j];
\}
MyModel.constraint (nbMachinesSelected =1); \}

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Flow line decomposition:

- Each station $s$ characterized by $\mathrm{E}\left[T_{s}\right]$ and $c_{s}^{2}$


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- Implemented in C++ as a LocalSolver native function
- Called by LocalSolver via API during during each LocalSolver search move


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Relaxation of integrality constraints

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$$
T_{s}=\sum_{j=1}^{J_{s}} \bar{v}_{s, j} \cdot T_{s, j}
$$

Important assumption: perfect correlation between $T_{s, i}$ and $T_{s, j}$ !!!!!

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(1) Phase II: Re-distribute current budget while $P R$ increases
(2) Phase III: Decrease budget until $P R \approx P R^{\text {min }}$
(5) Terminate when budget stops to decrease for feasible solution or when $P R^{\min }$ is not reached in Phase I

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Observation: Relaxed selection variables $\bar{v}_{s, j}$ often binary, buffer variables $\bar{x}_{s}$ never

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Steepest ascent method
(1) PR highly non-linear, frequent gradient updates
(2) Termination, numerical issues

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## An extremely preliminary conclusion

First impression from Branch \& Bound

- Methods seems to work (in principle)
- Algorithm complex and not yet stable
- First feasible solutions can be found quickly
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Future work

- Improve stability
- Serious numerical study
- Model variants, e.g., space limitations


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Thank you!!

