



Considering Sequence-Dependent

Stochasticity in Production Schedules

Michael Manitz

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Joint work with:

- Frank Herrmann (OTH Regensburg)
- Maximilian Munninger (Duisburg/Essen University)



A (simpliest) example 2 Stages



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Index Sets

 $\mathcal K$... 3 products: $k=\mathsf{A1}$ and $k=\mathsf{B1}$ and $k=\mathsf{C1}$

 \mathcal{N}_k ... the components k that are needed for the final production process; $\mathcal{N}_{A2} = \{A1\}, \ \mathcal{N}_{B2} = \{B1\}, \ \mathcal{N}_{C2} = \{C1\}, \ \mathcal{N}_{A1} = \mathcal{N}_{B1} = \mathcal{N}_{C1} = \emptyset$

 ${\cal J}$ \ldots 2 bottleneck machines whose limited capacity concerns

Parameters

- d_{kt} ... demand for product k in period t
- s_k ... setup costs for product k
- h_k ... holding costs for product k

 tb_{jk} ... processing time per unit for product k on machine j

- tr_{jk} ... setup time for product k on machine j
- b_{jt} ... available capacity of machine j in period t
- z_k ... pre-specified lead time for product k



$$\label{eq:minimize_costs} \text{Minimize costs} \quad Z = \sum_{k \in \mathcal{K}} \sum_{t=1}^T \left(h_k \cdot y_{kt} + s_k \cdot \gamma_{kt} \right)$$

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$$y_{k,t-1} + q_{k,t-z_k} - \sum_{i \in \mathcal{N}_k} a_{ki} \cdot q_{it} - y_{kt} = d_{kt} \qquad (k \in \mathcal{K}; t = 1, 2, \dots, T)$$

Capacities in period *t*:

$$\sum_{k \in \mathcal{K}} \left(\mathsf{tb}_{kj} \cdot q_{kt} + \mathsf{tr}_{kj} \cdot \gamma_{kt} \right) \le b_{jt} \qquad (j \in \mathcal{J}; t = 1, 2, \dots, T)$$

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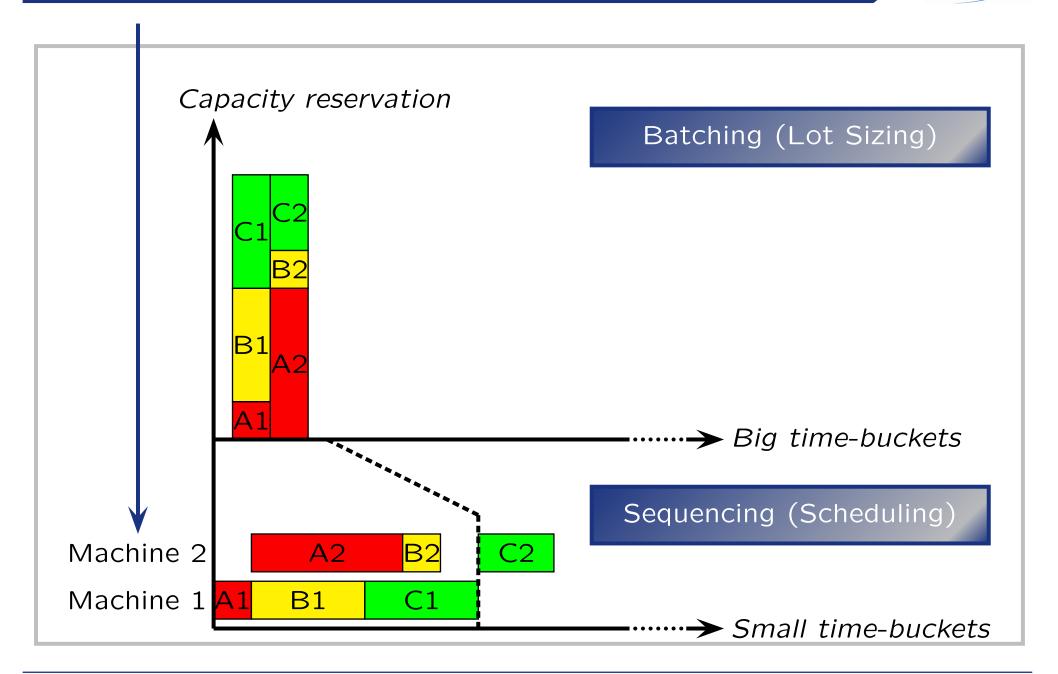
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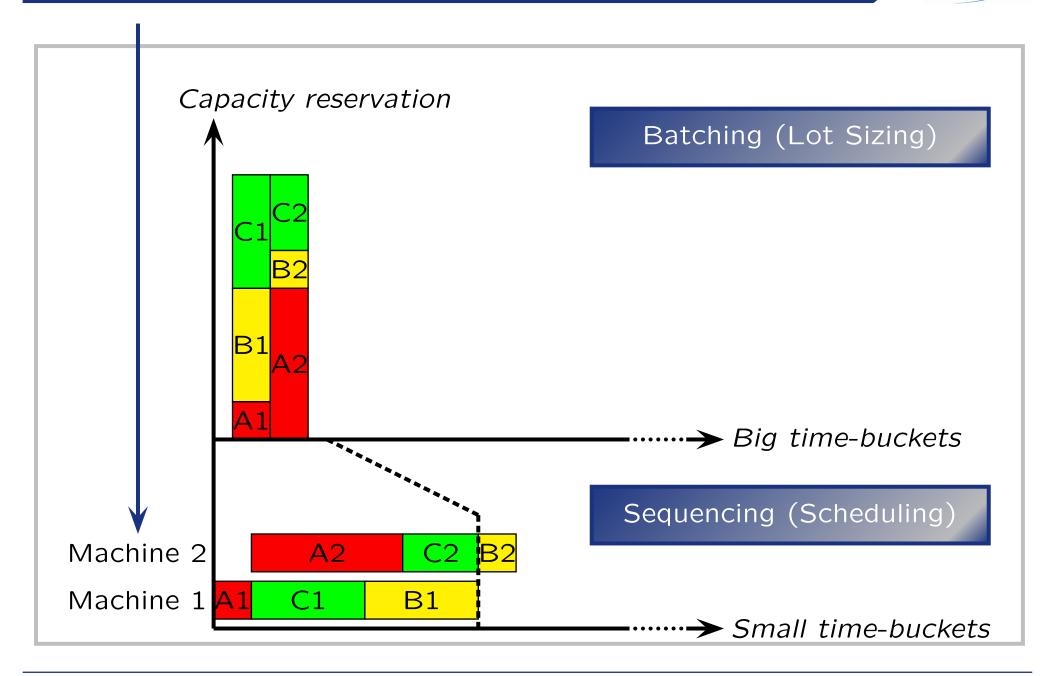
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The situation in production planning & control:



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Why Stochasticity in a Deterministic Model?



Why the implementation of the production schedules from a deterministic optimization model leads to stochastic results?

[Even if all the parameters are assumed to be deterministic!]

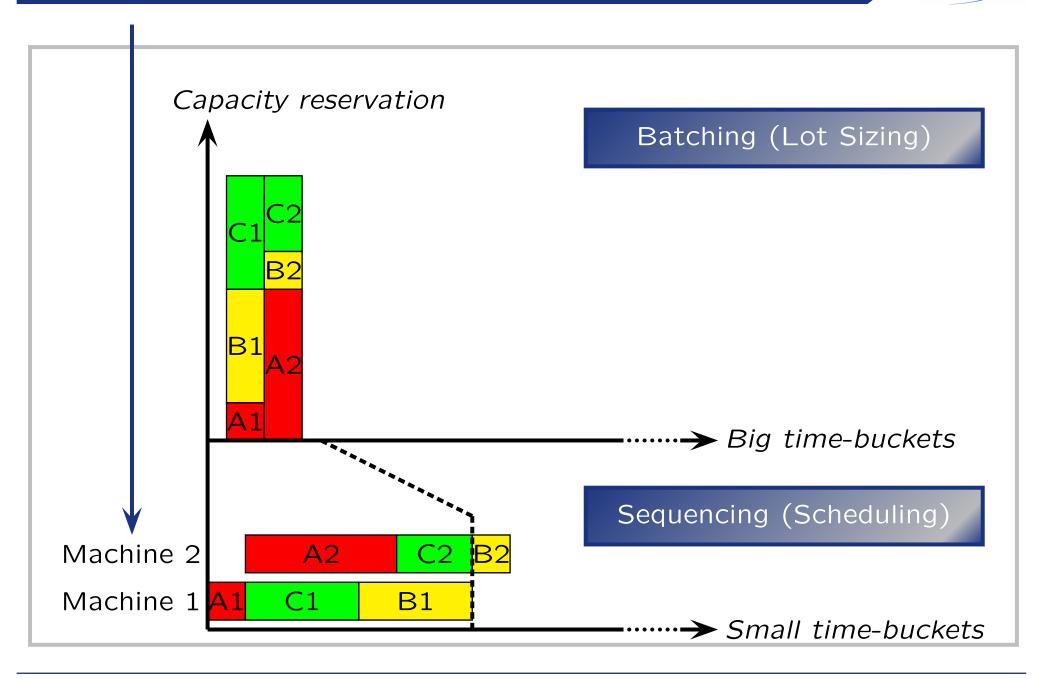
- •••
- sequencing rules
- sequencing constraints

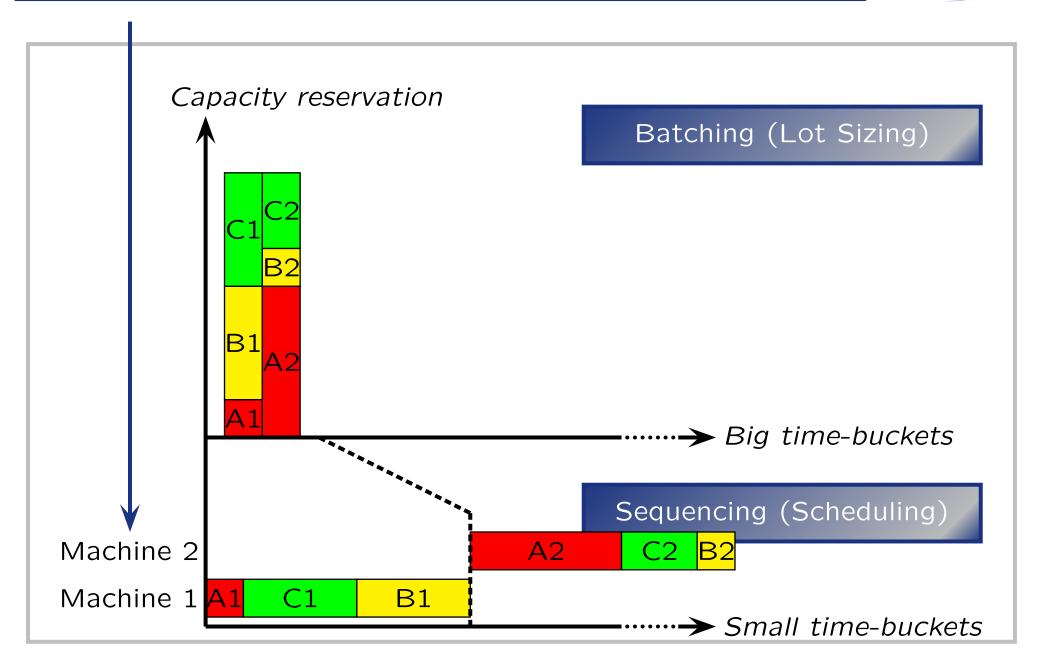
The results of their application later on are not known during the roughcut capacity planning (big-bucket model) and, hence, are unpredictable and—finally—stochastic.





Augmenting the planned lead times—with or without doing anything—is the wrong answer.











SBC: Stationary Backlog-Carryover (Stolletz (2008))



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We take the rates over the planning horizon from the given workload

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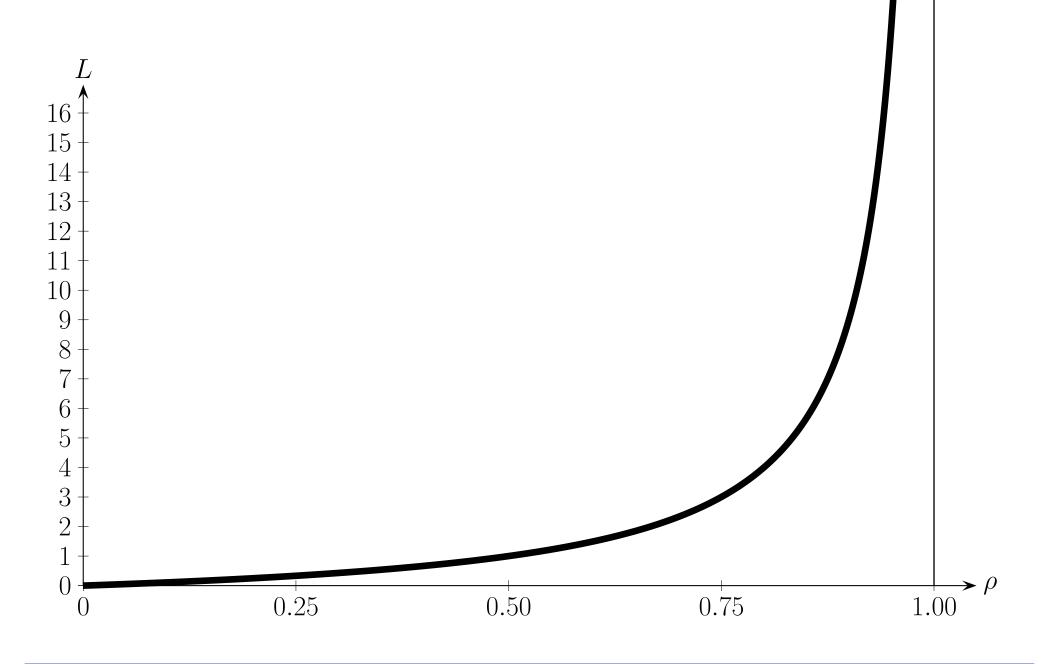
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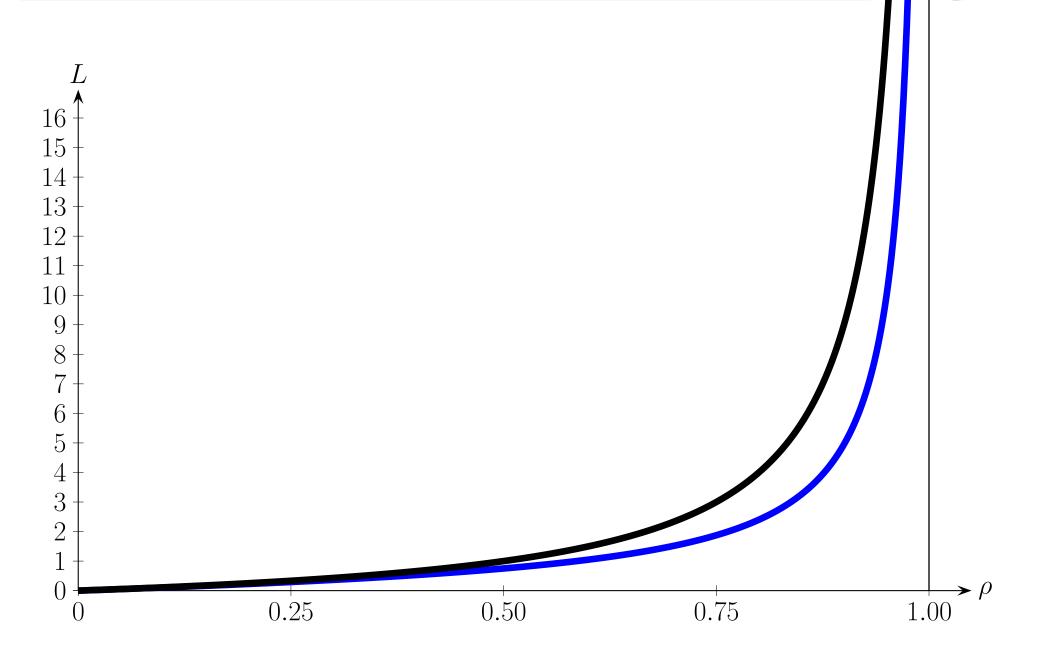
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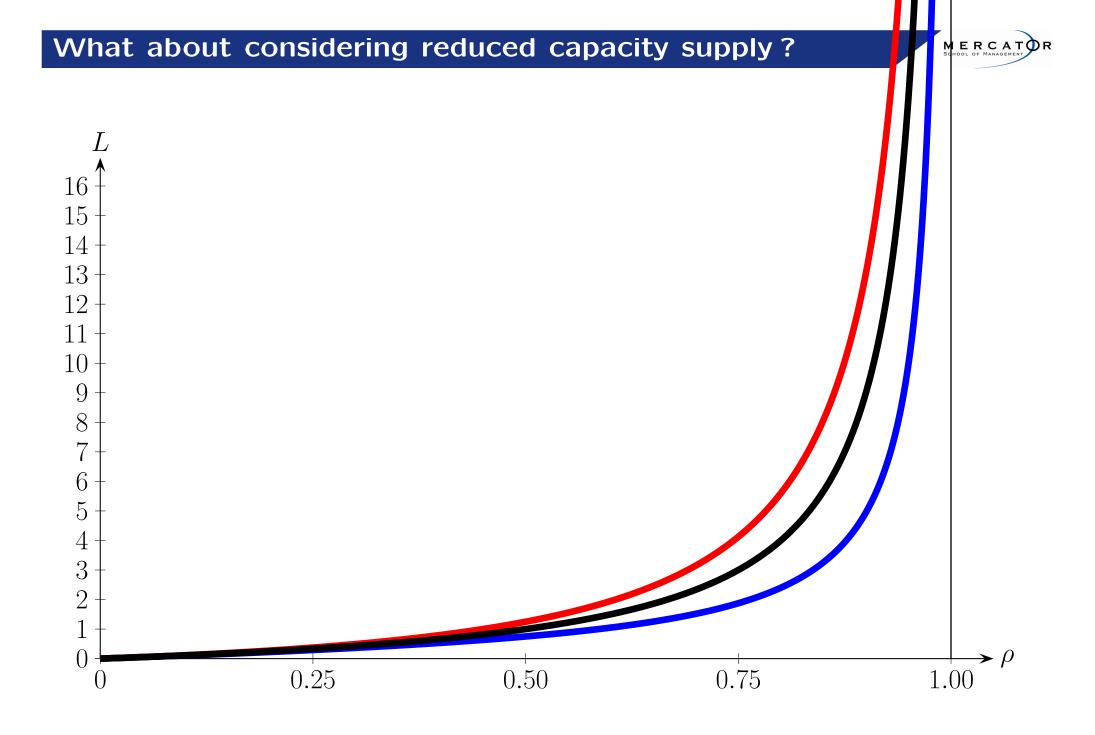
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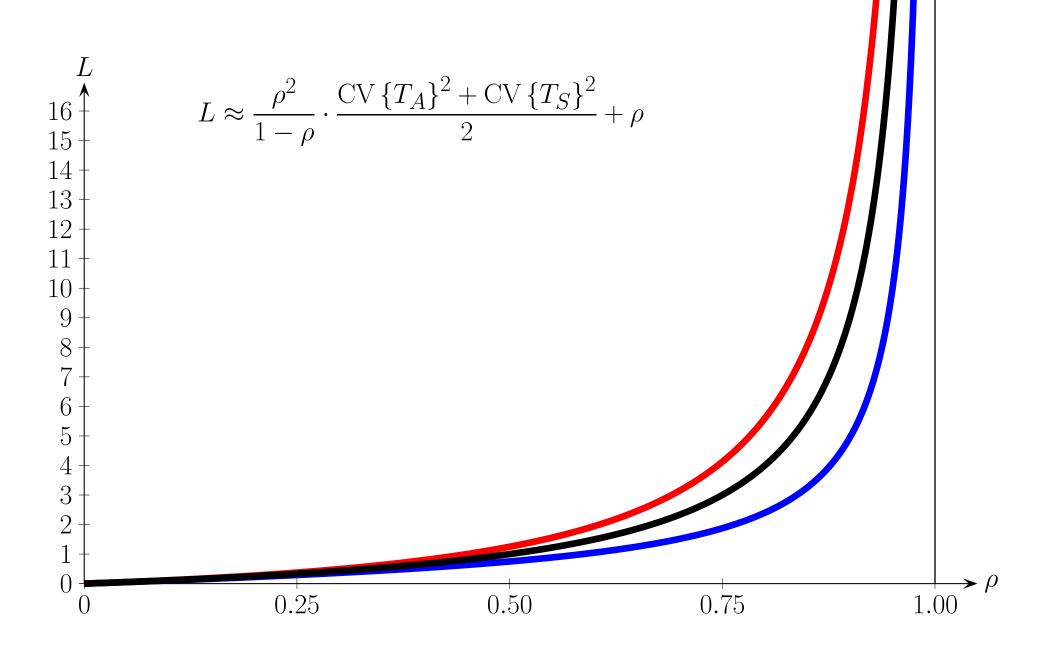


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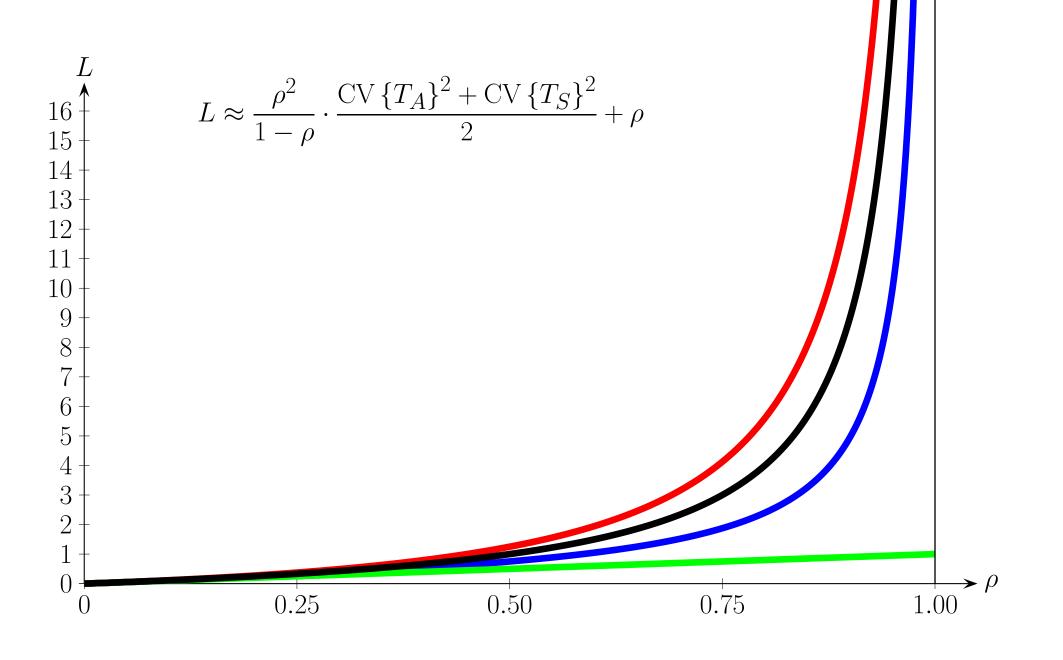


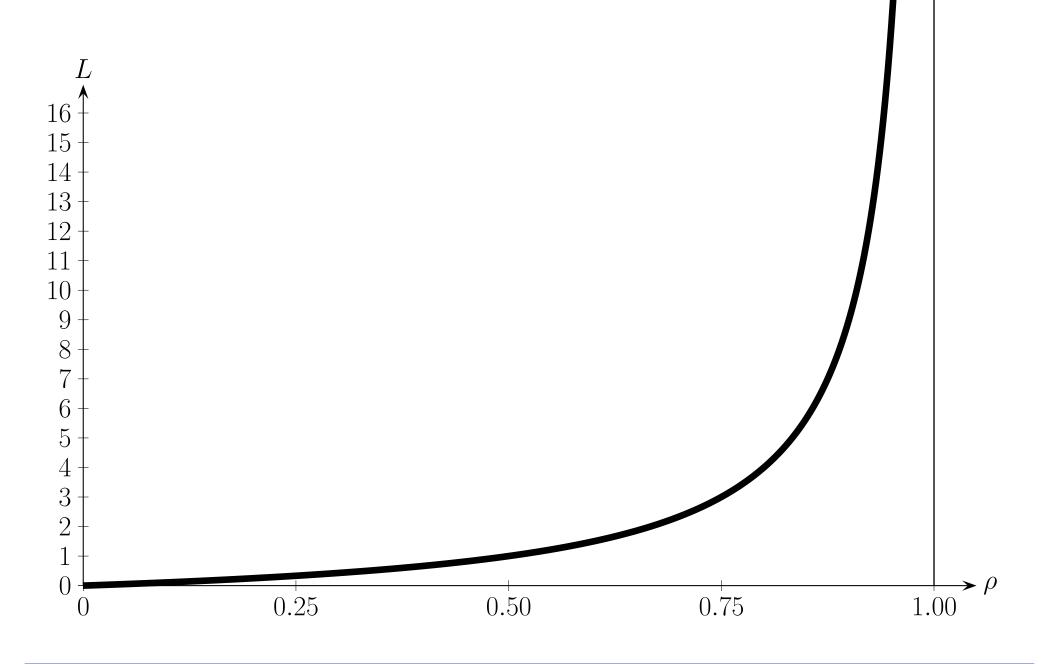
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SMMSO, Acaya, June 2017

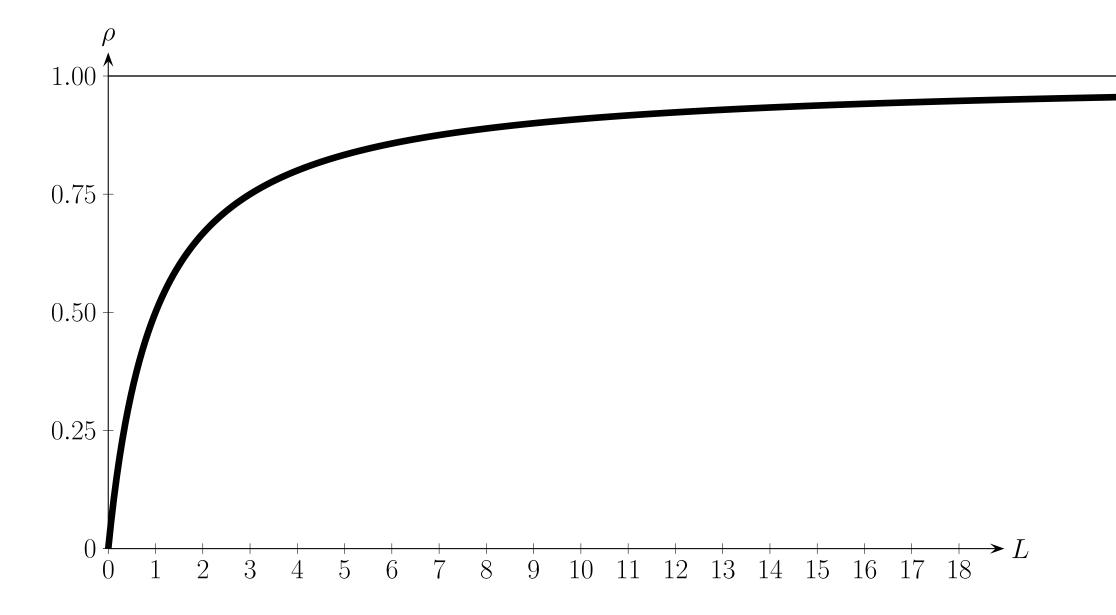


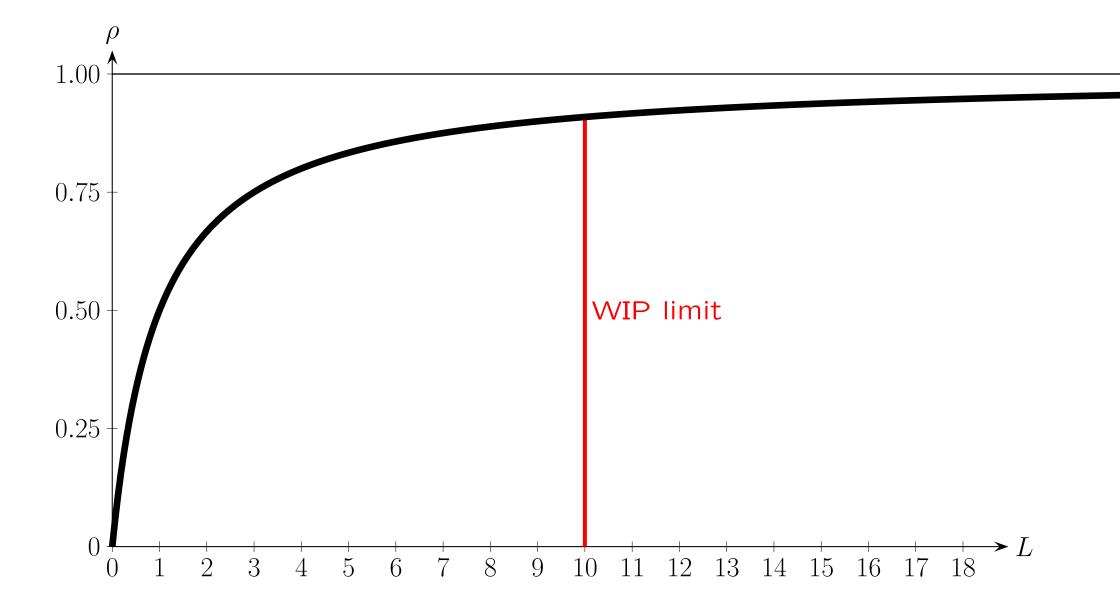
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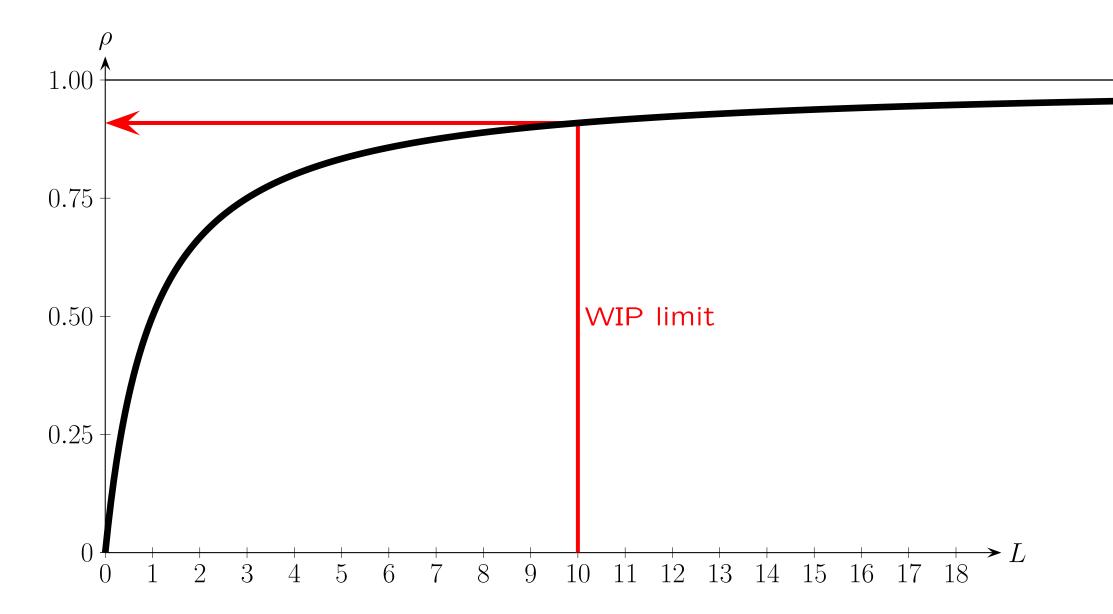




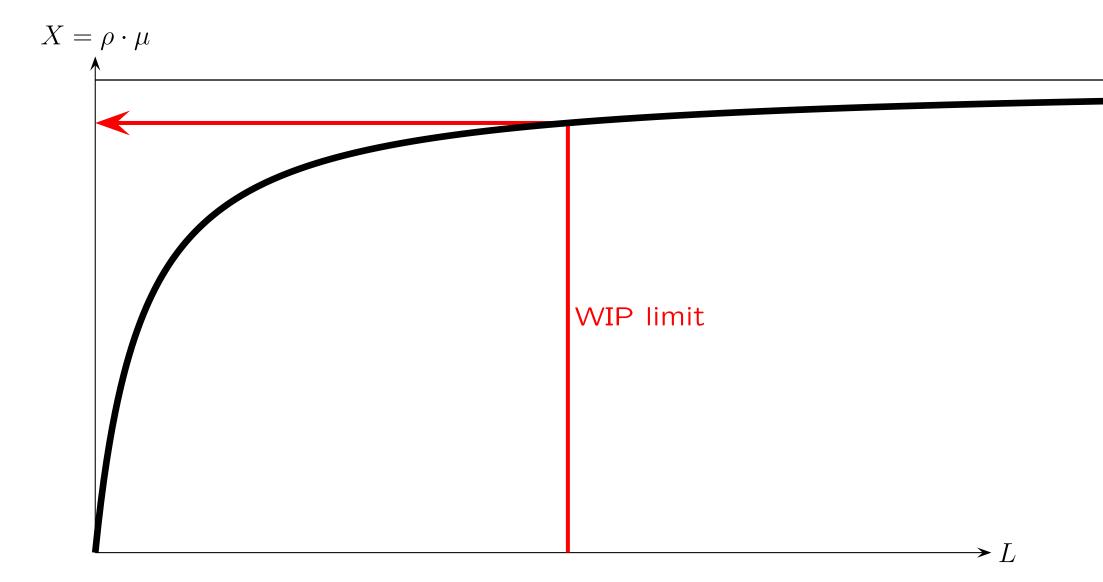
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A Clearing Function might help.





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Production-quantity limit:

$$w_{kt} = q_{kt} - X(q_{kt})$$

Effective capacity loss:

$$V_{jt} = \sum_{k \in \mathcal{K}} w_{kt} \cdot \mathsf{tb}_{jk}$$

 $(k \in \mathcal{K}; t = 1, 2, \dots, T)$

$$(j \in \mathcal{J}; t = 1, 2, \dots, T)$$



MLCLSP

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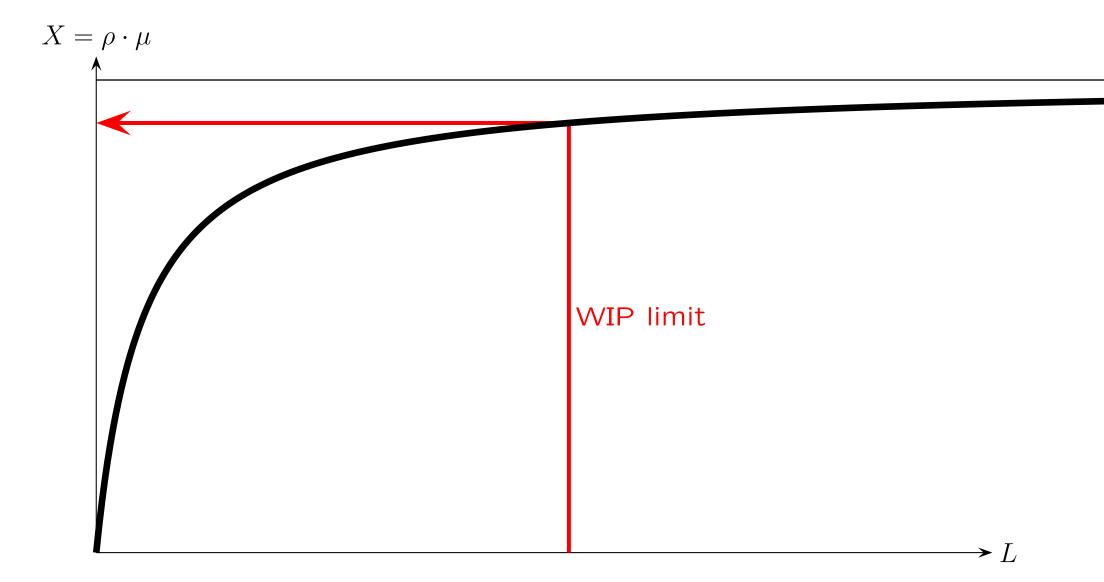
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160,00

140,00

120,00

100,00

80,00

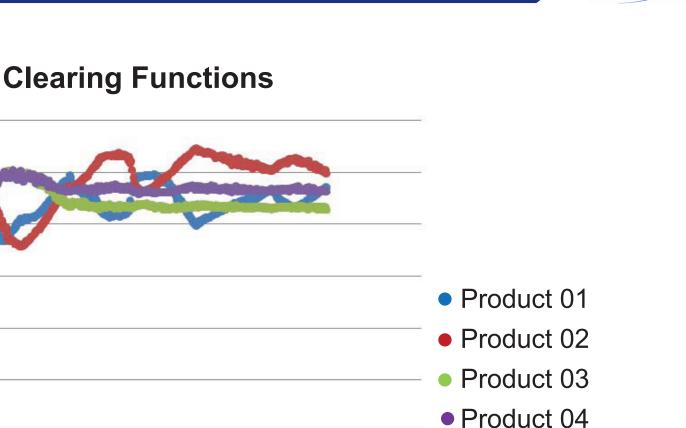
60,00

40,00

20,00

0,00

Output E(X_k)



0,00

100,00

200,00 300,00

WIP E(W_k)

400,00

600,00

500,00









MLPLSP

Too complicated !



MLPLSP

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computational times



MLPLSP

Too complicated !

- computational times
- practical application





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We cannot guarantee a feasible solution for the scheduling problem.